

End-to-end CNN with Selective Kernel Based Fusion and Inverse Tone-mapping Based Up-sampling for High-resolution HDR Imaging of Dynamic Scenes

鄧逸鵬 池永研究室 修士課程修了

Background

Ghost problem of HDR reconstruction



Dynamic LDR Images Result with ghost

Problem

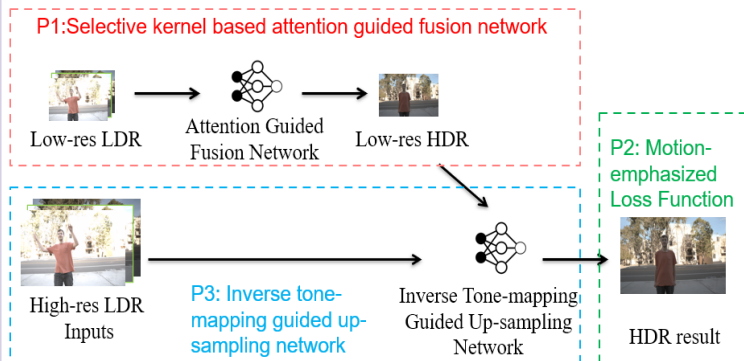
- ① Information Loss and extra time cost by pre-alignment
- ② Information utilization unbalance in motion areas
- ③ Ghost-like artifacts in the guide image generation

Solution

- **Proposal 1:** Selective kernel based attention guided fusion network
- **Proposal 2:** Motion-emphasized loss function
- **Proposal 3:** Inverse tone-mapping guided up-sampling network

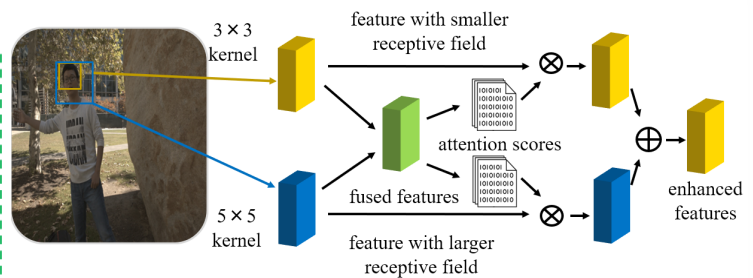
Proposals

Basic framework:



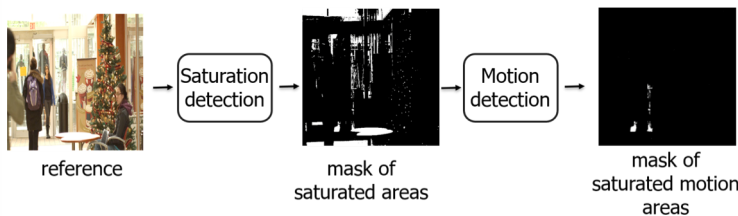
1.1 Selective Kernel Based Channel Attention Module

➤ Robustness with selective kernel channel attention module



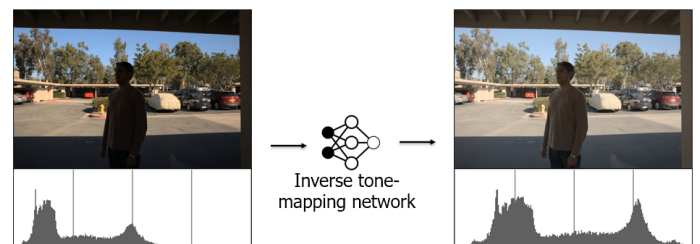
2. Motion-emphasized Loss Function

➤ Saturated motion mask with larger weights



3. Inverse Tone-mapping Based Up-sampling

➤ Enhancement of LDR's dynamic range



Experiment result

	Sen12	Kalantari17	Wu18	Yan19	Ours
PSNR(T)	40.9545	42.7423	41.7403	42.9167	43.1733
PSNR(L)	38.3156	41.2158	40.8739	40.1648	40.8990
HDR-VDP-2	56.8968	60.5088	60.5006	60.8320	61.0222

Conclusion

The proposed method scores 43.17 with PSNR metric and 61.02 with HDR-VDP-2 metric on test which outperforms all conventional works.

And with an up-sampling module, the proposed network produces HDR at an 80% time off with quality degradation from 43.17 to 38.16 in PSNR.

